



Construction Process Modelling: Representing Activities, Items and their Interplay.

Elisa Marengo, Werner Nutt and Matthias Perktold
Faculty of Computer Science, Free University of Bolzano



Construction Projects are “Rarely” On-Time/On-Budget

- Wembley National Stadium
 - Commenced: 2002
 - Planned Completion: Early 2006
 - Opened: March 2007
 - *Delay: 1 year*
 - Planned Cost: £757m
 - Final Cost (approx.): £1bn
 - *Increased cost: 32%*



Construction Projects are “Rarely” On-Time/On-Budget

- Berlin Airport
 - Commenced: 2006
 - Planned Completion: 2011
 - Opened: ??? (2020)
 - *Delay: 9 Years*
 - Planned cost: €2bn
 - Current Cost: €6bn
 - *Increased cost: 200%*

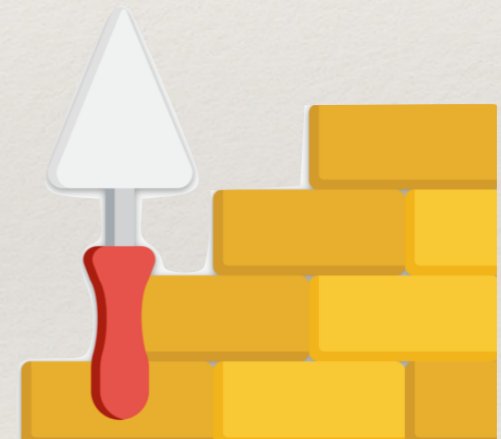


<https://www.economist.com/the-economist-explains/>

Why Are They Special?

In Construction

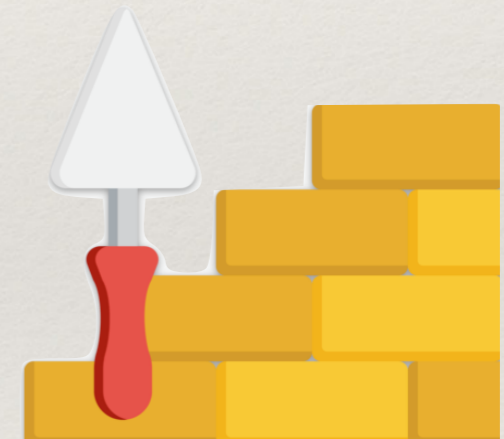
- Projects are one of a kind
(difficult to make estimates)



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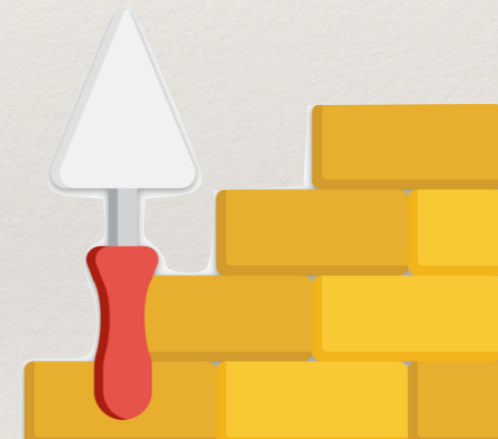
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- Many companies are involved



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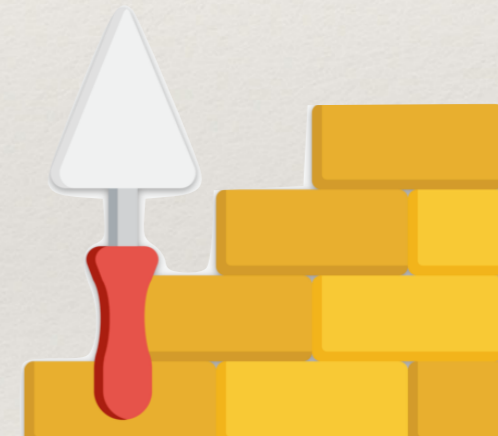
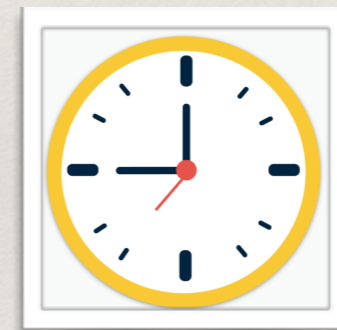
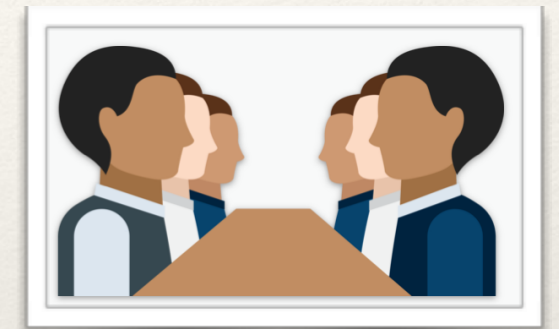
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- Many companies are involved
- Unpredictable events



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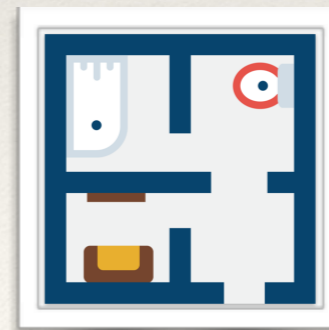
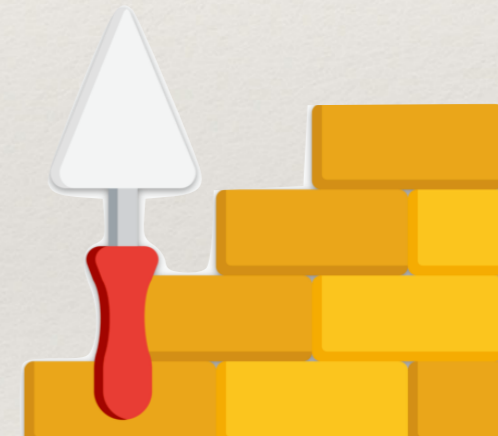
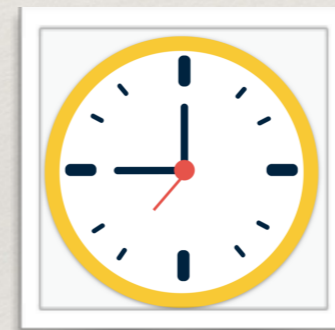
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- Many companies are involved
- Unpredictable events
- Projects are complex and long



Why Are They Special?

In Construction

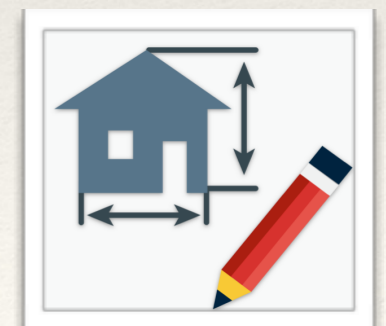
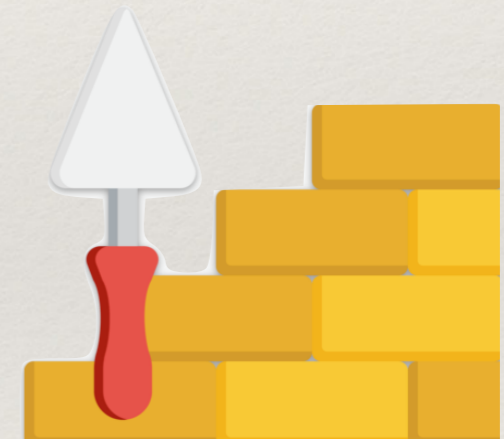
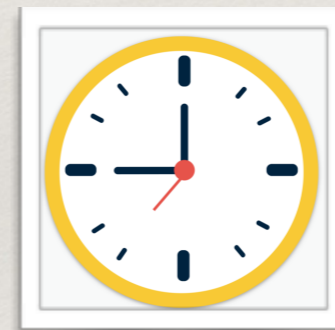
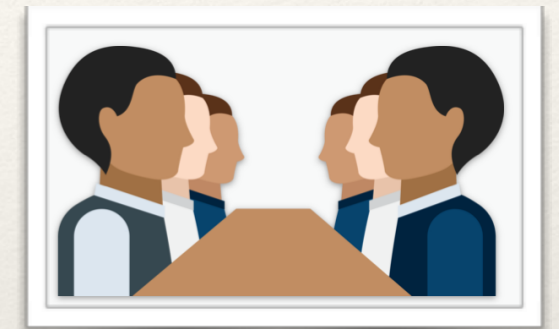
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- Projects are complex and long
- Shared resources/locations



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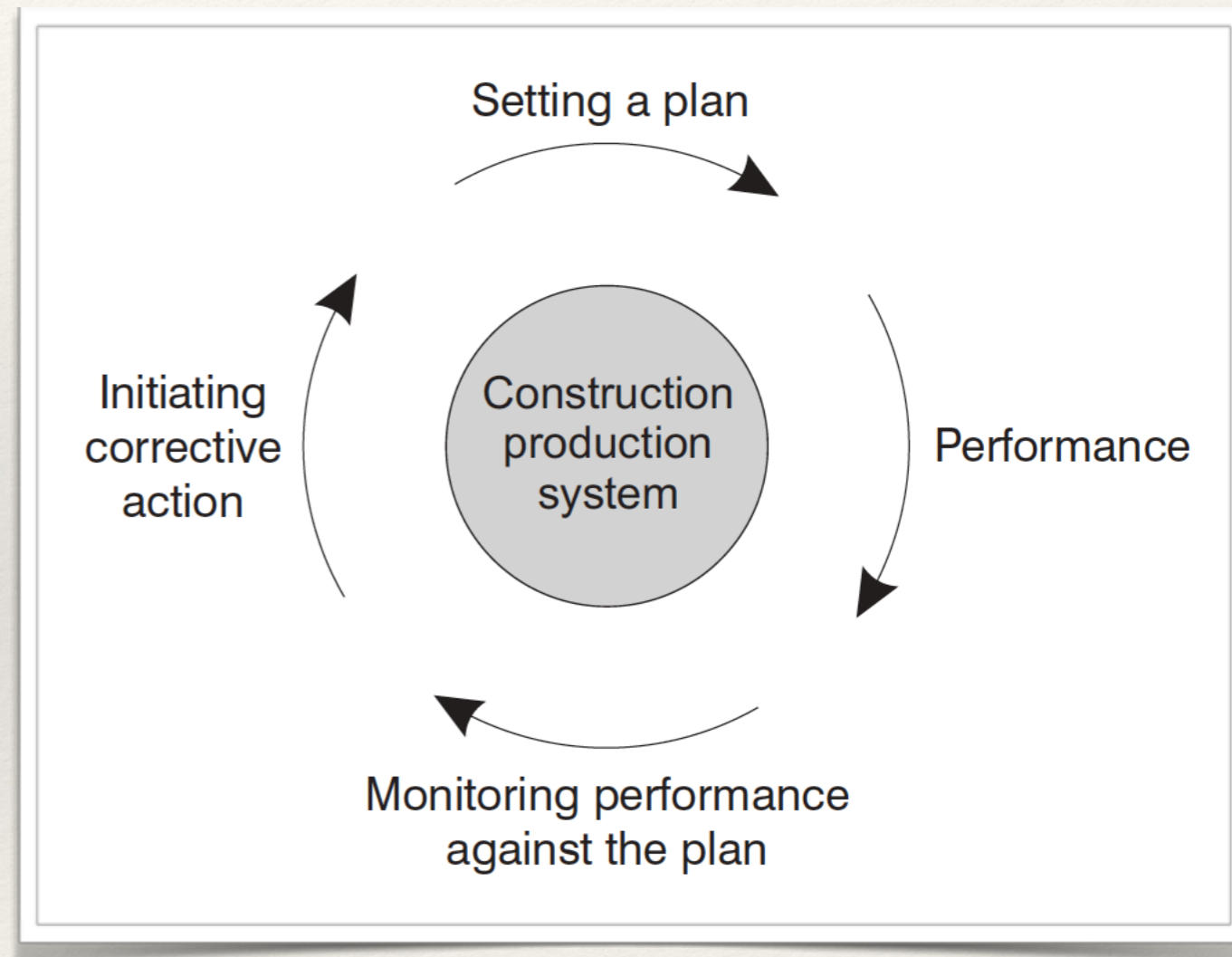
In Construction

- Projects are one of a kind (difficult to make estimates)
- Many companies are involved
- Unpredictable events
- Projects are complex and long
- Shared resources/locations
- Changing requirements



Traditional Approach

- **Planning:**
 - Define the activities, orders in which they occur and milestones
- **Scheduling:**
 - Define timetables
- **Control:**
 - Detect deviations from the plan

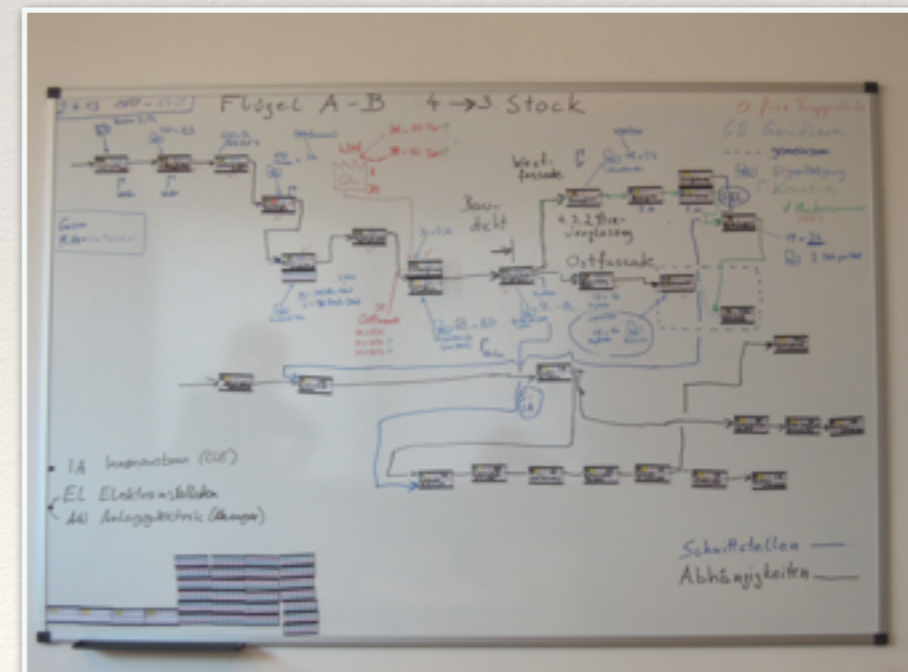


Traditional Approach: Some Considerations

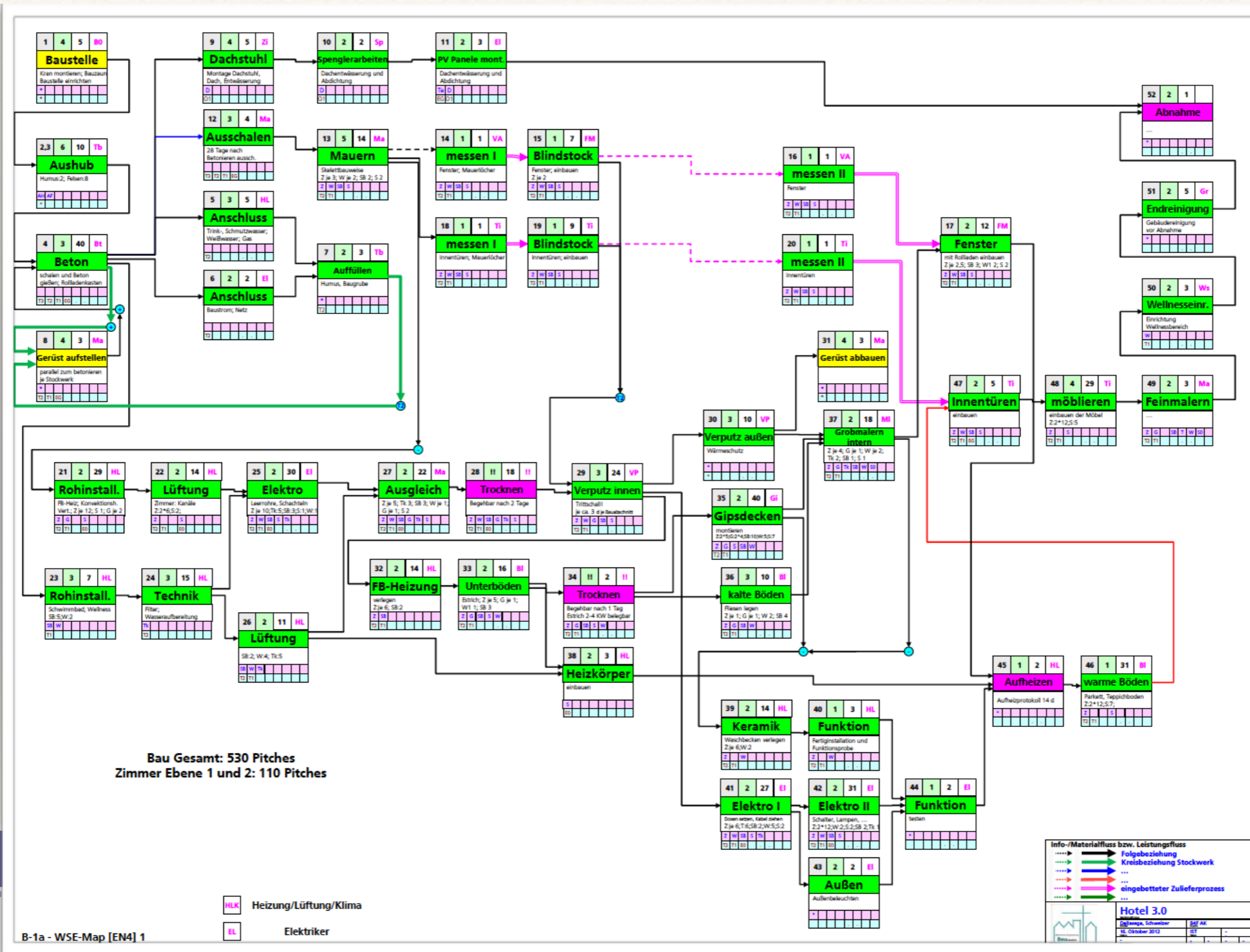
- **Locations:**
 - Physical locations are not considered explicitly
 - No location-based relationship between the activities
- **Planning as Gantt Chart:**
 - Represent a commitment to a date
 - Lack of flexibility: not clear what are the dependences
 - Become outdated very soon
 - Never updated

Tentative Solution

- Planning
 - Decoupled from scheduling
 - Define **What** and **Where** (not yet when)
 - Collaborative modelling



Hospital of Bolzano



Elements in the model

- Tasks
 - What: Activity
 - Who: Craft
 - Where: Locations
 - How long: Productivity
 - Notes

Productivity

#184	2	5	FL
LF - Lay Floor			
Z	G	W	
T1	T2	*	

Craft

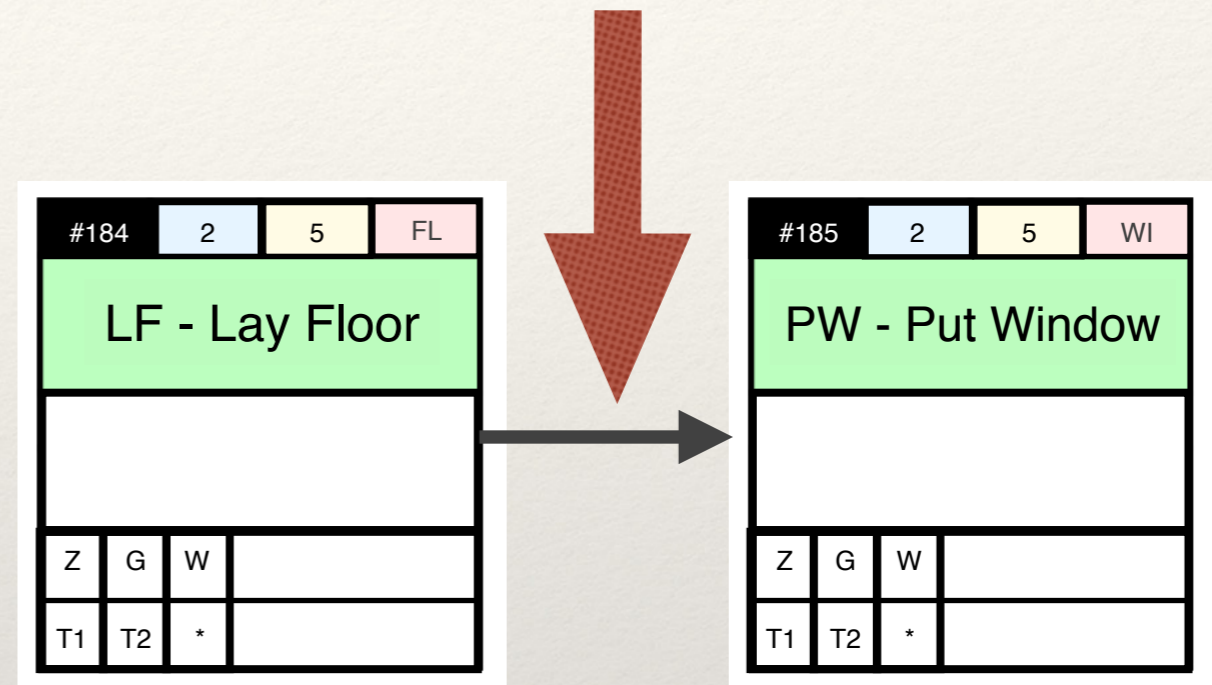
Activity

Notes

Locations

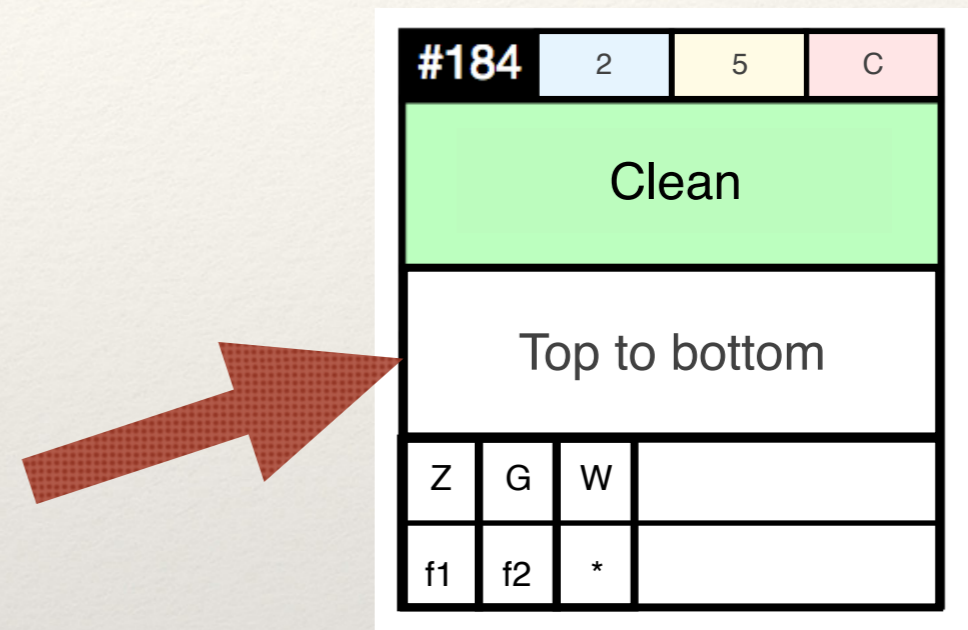
Elements in the model

- Tasks
 - What: Activity
 - Who: Craft
 - Where: Locations
 - How long: Productivity
 - Notes
- Synchronisation
 - Declarative precedences



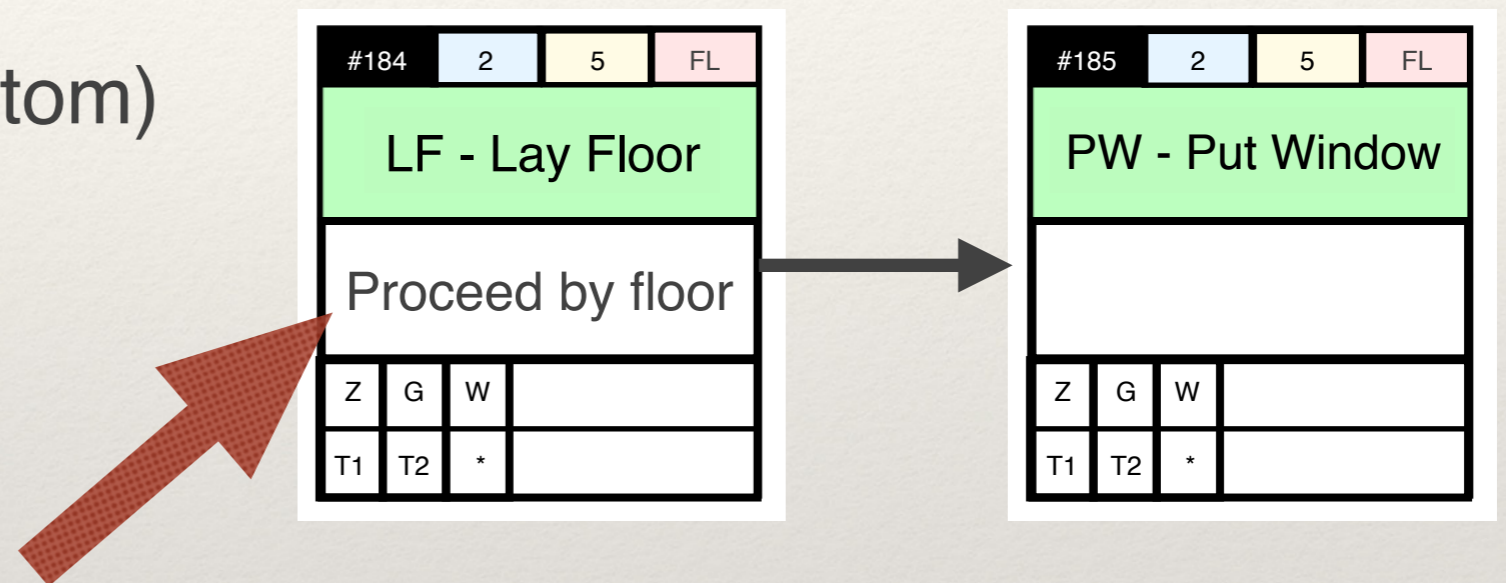
Hidden Knowledge and Ambiguities

- **Orderings**
among the locations
(bottom to top, top to bottom)



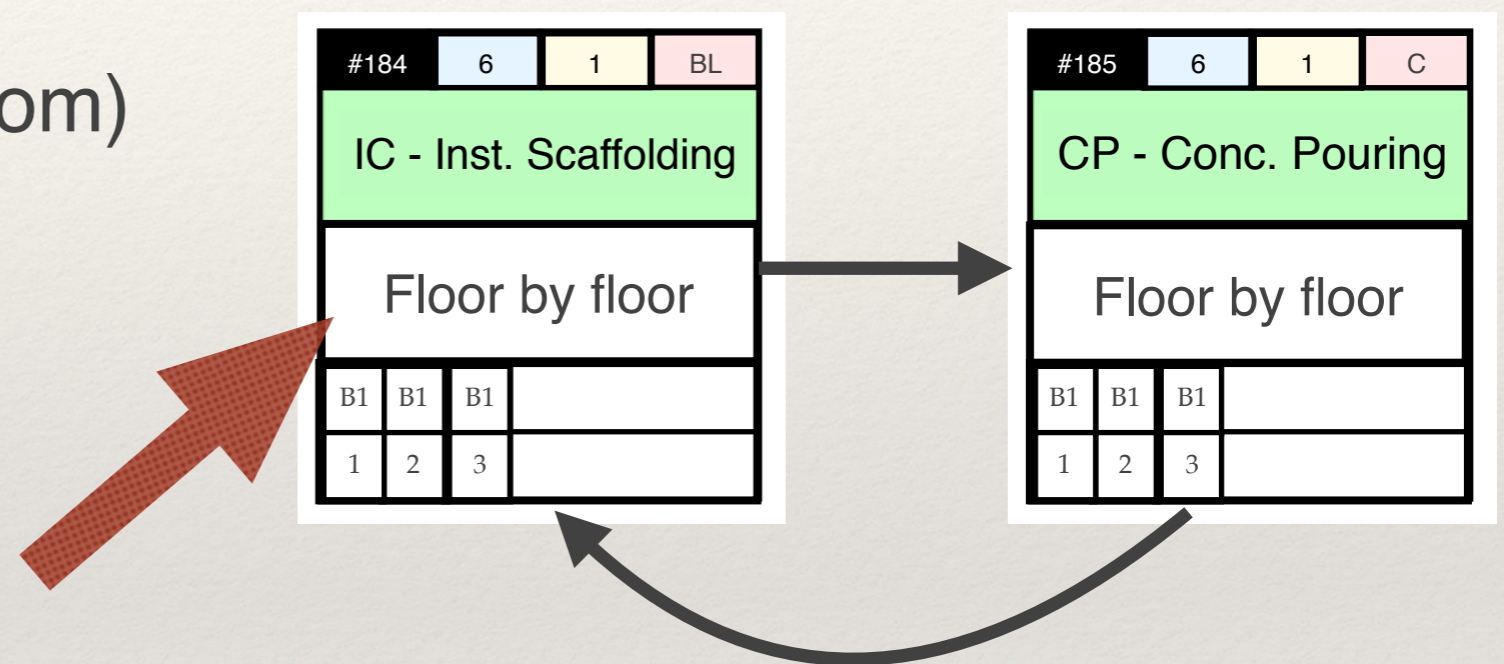
Hidden Knowledge and Ambiguities

- **Orderings**
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- Precedence **Scope**
(floor, activity, building)



Hidden Knowledge and Ambiguities

- **Orderings**
among the locations
(bottom to top, top to bottom)
- Precedence **Scope**
(floor, activity, building)
- How to perform **Loops**

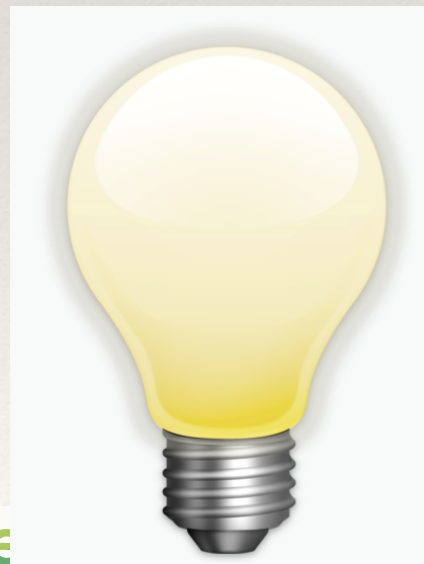


How to Schedule?

- Preconditions for **manual** and **automatic** scheduling
 - Represent explicitly the hidden knowledge
 - Make the language non-ambiguous (Formal)

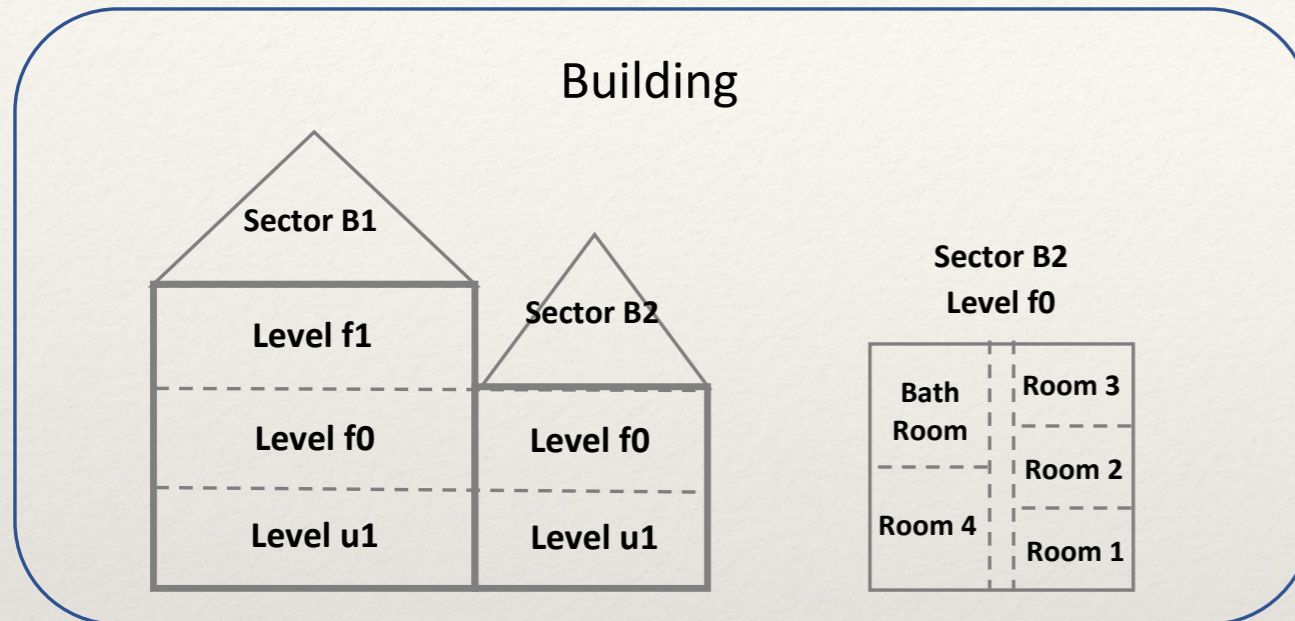
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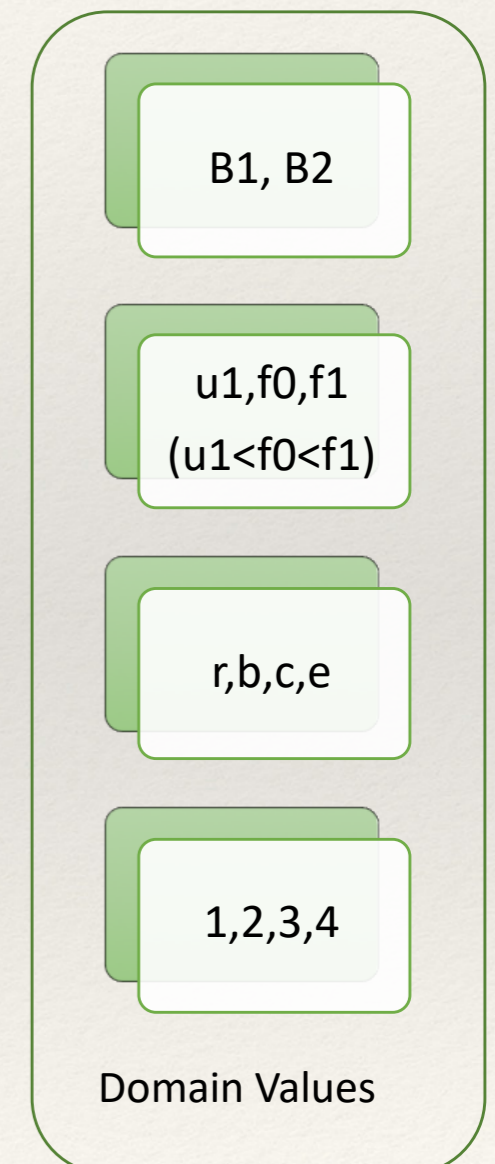
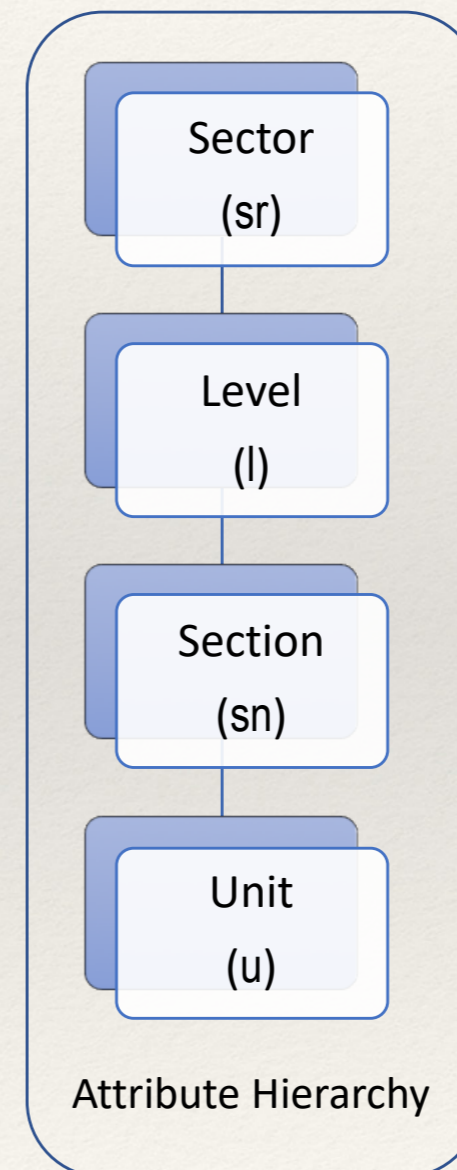
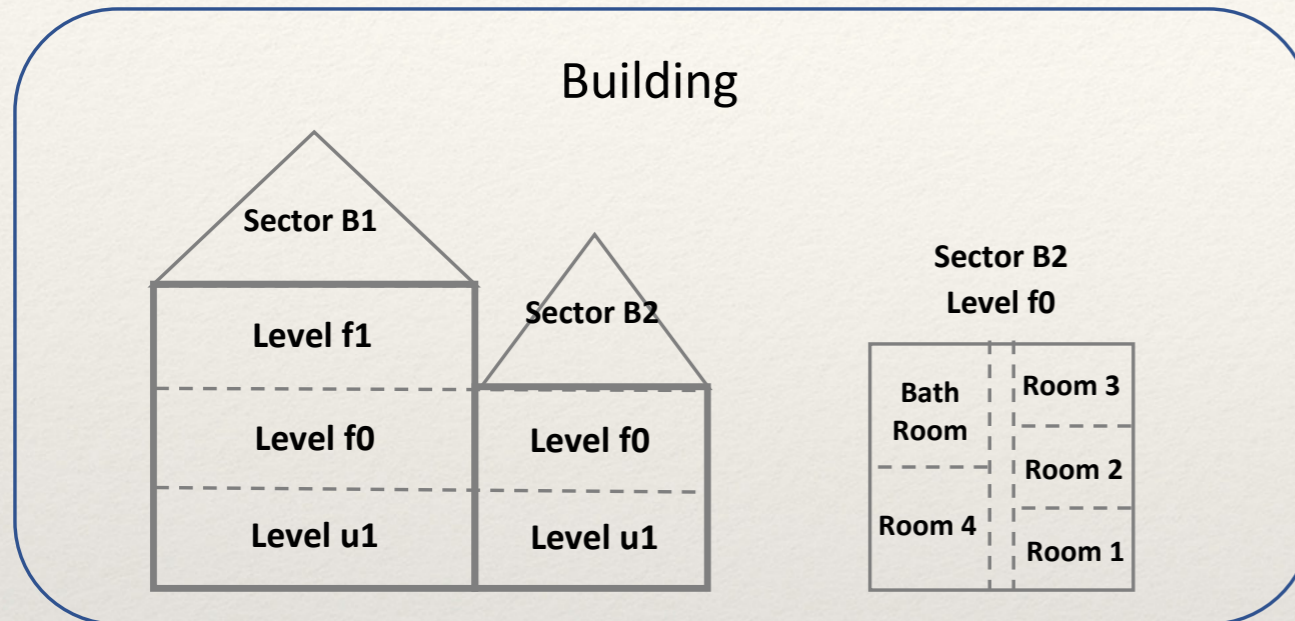


- We extended the language (inspired by Declare)
- Provide a logic-based (LTLf) semantics

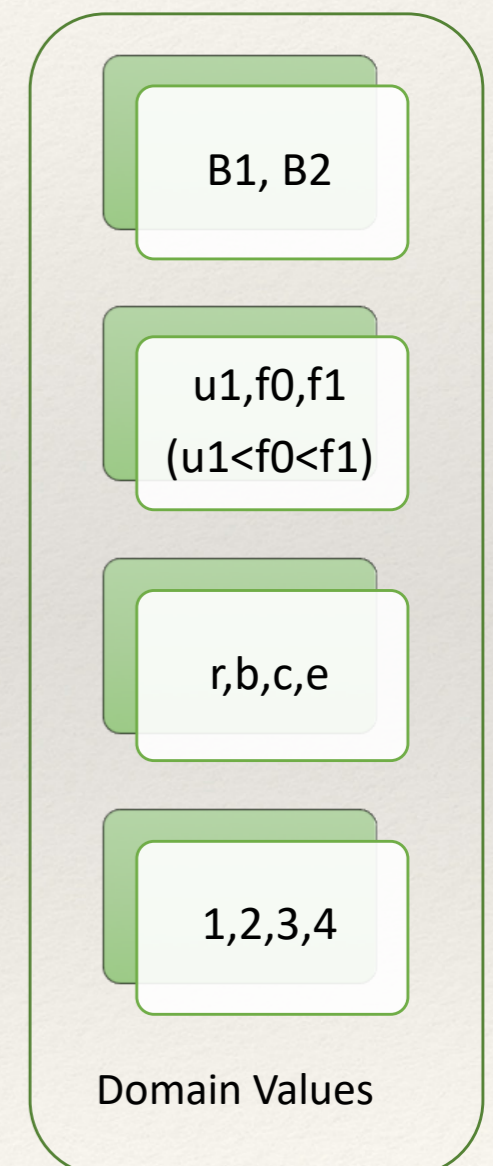
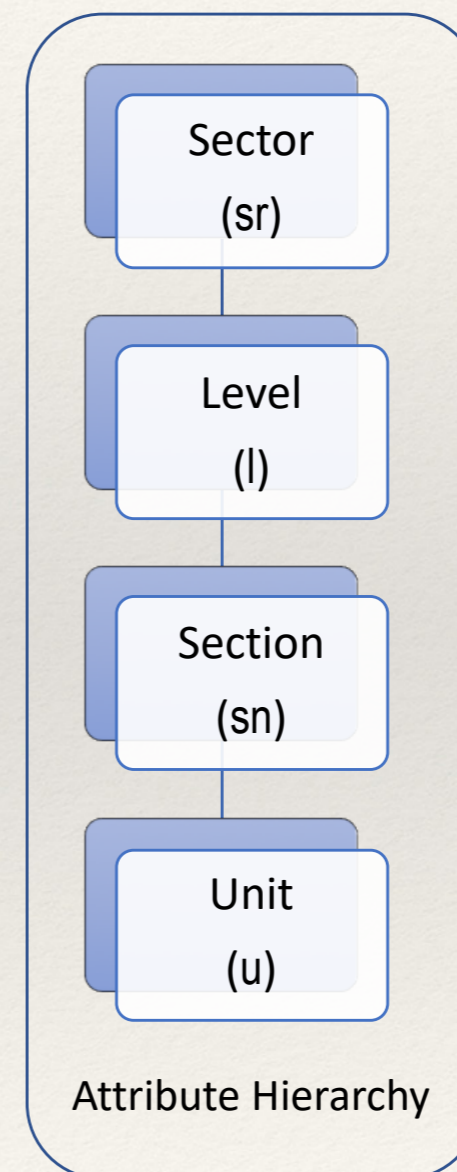
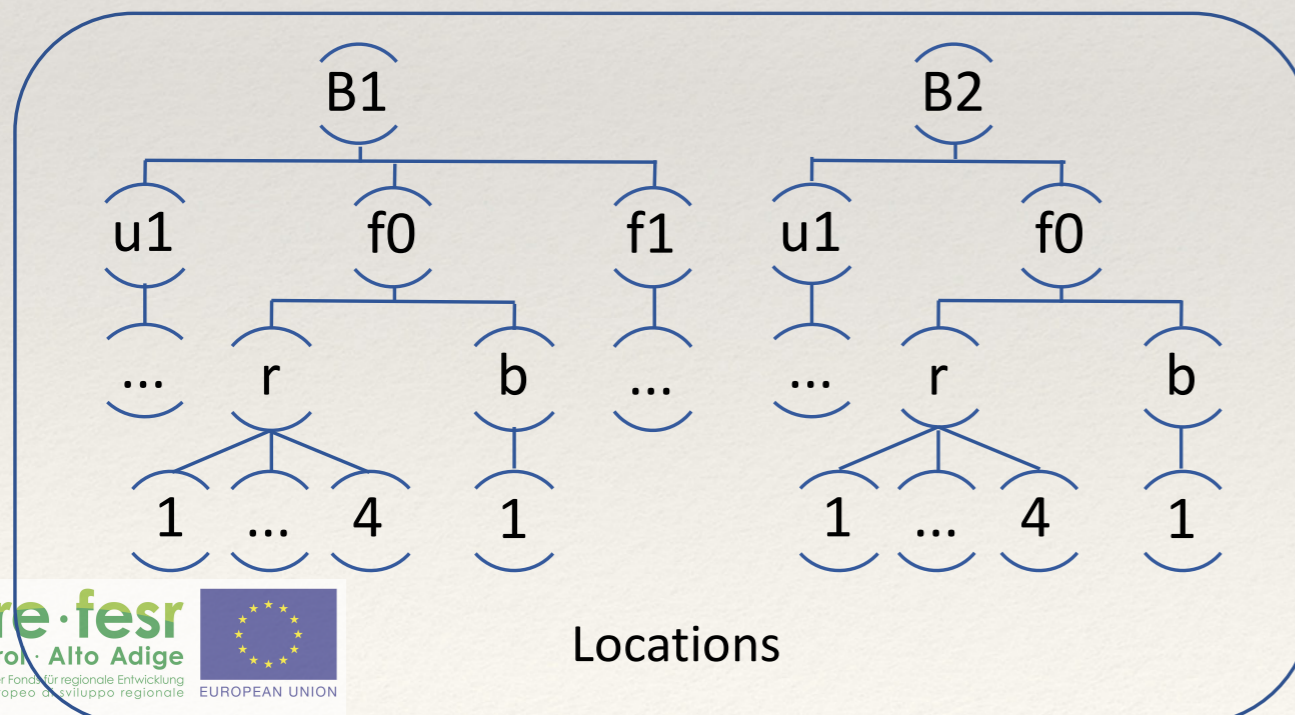
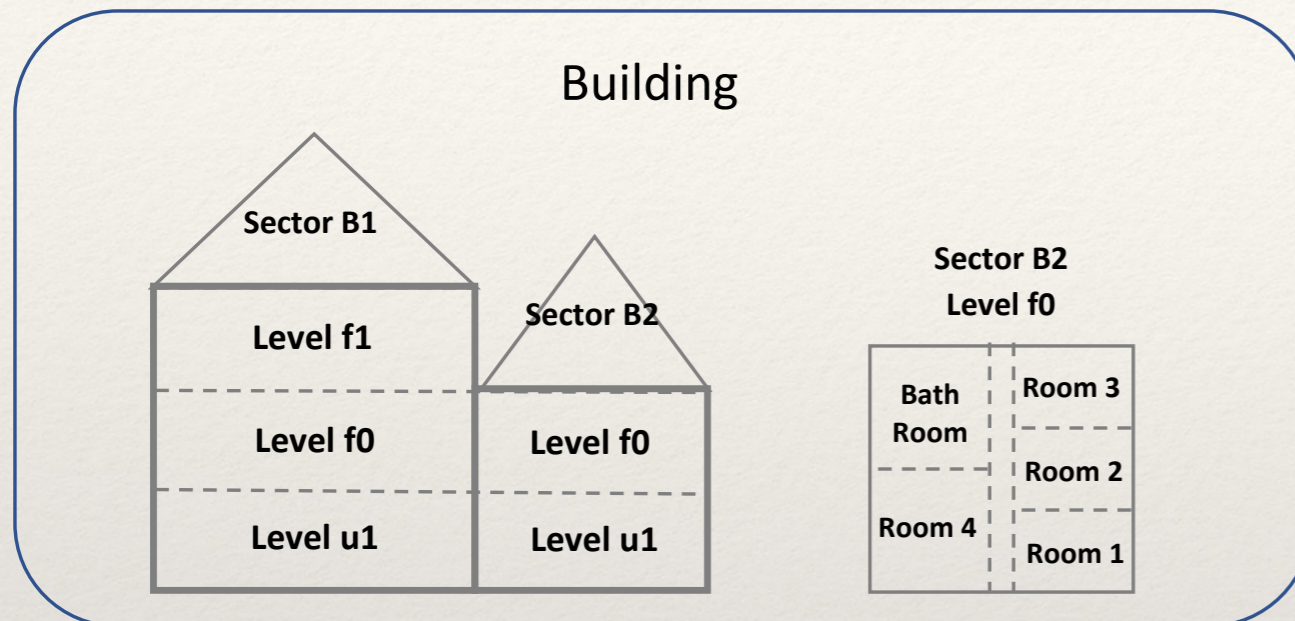
Customisable Building Representation



Customisable Building Representation

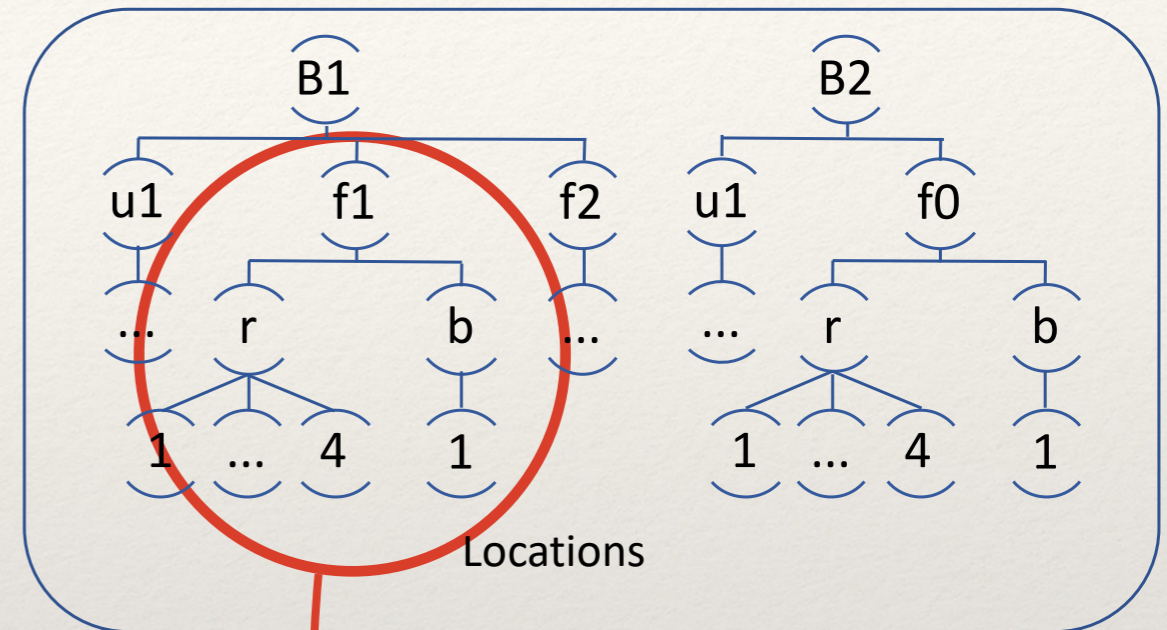


Customisable Building Representation



Representation of Locations

- A building is abstractly represented as a tree
- Locations in the tasks are **subtrees**




$\langle B1, f1, r, * \rangle$
 $\langle B1, f1, b, * \rangle$

#113	1x2	60d	FL	
LF - Lay Floor				
<: NONE	ex: sr,l			
B1	B1	B1	B2	B2
f0	f1	f1	f0	f0
e	r	b	r	b
1	*	*	*	*

Ordering Constraints

- Attribute domain values can be ordered
- **Ascending** and **descending** ordering constraints

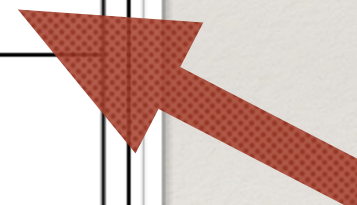


#148	1x1	20d	Sc
SI - Scaffolding Installation			
<: ↑		ex: UNIT	
B1	B1	B2	
f0	f1	f0	

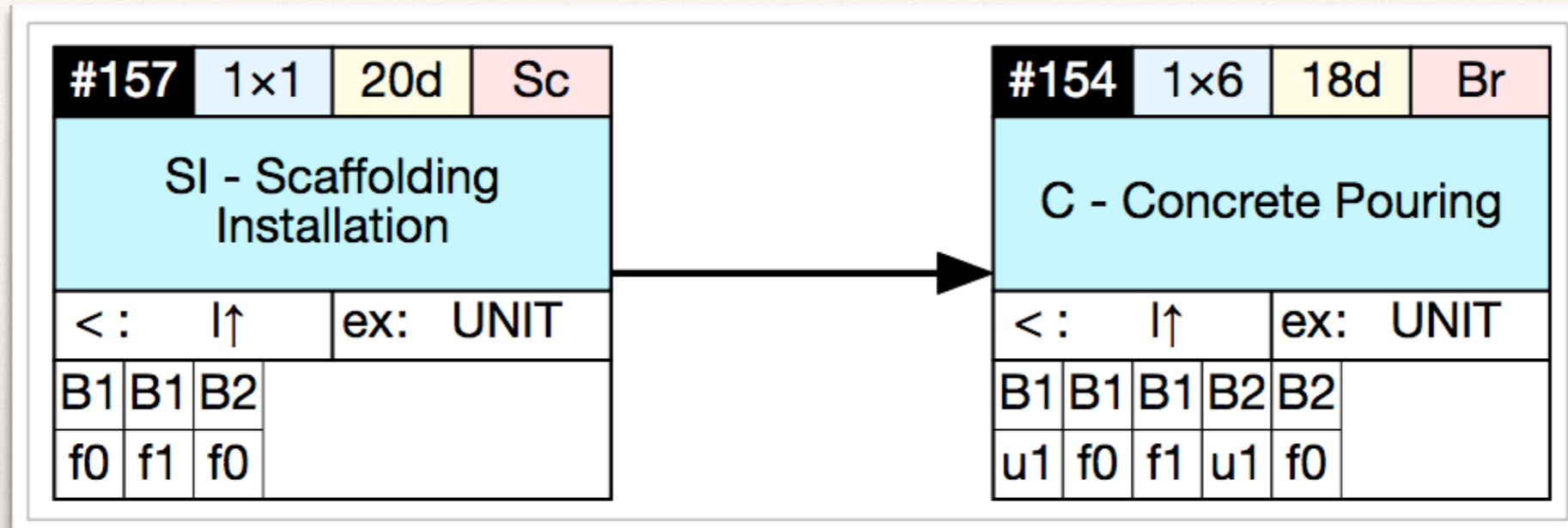
Exclusivity Constraints

- Once the task is started, **no other task** can be performed there
- By default: exclusivity at the **unit level**

#143	1x6	10d	Di
Ex - Excavation			
< : NONE		ex:	sr
B1	B2		
u1	u1		

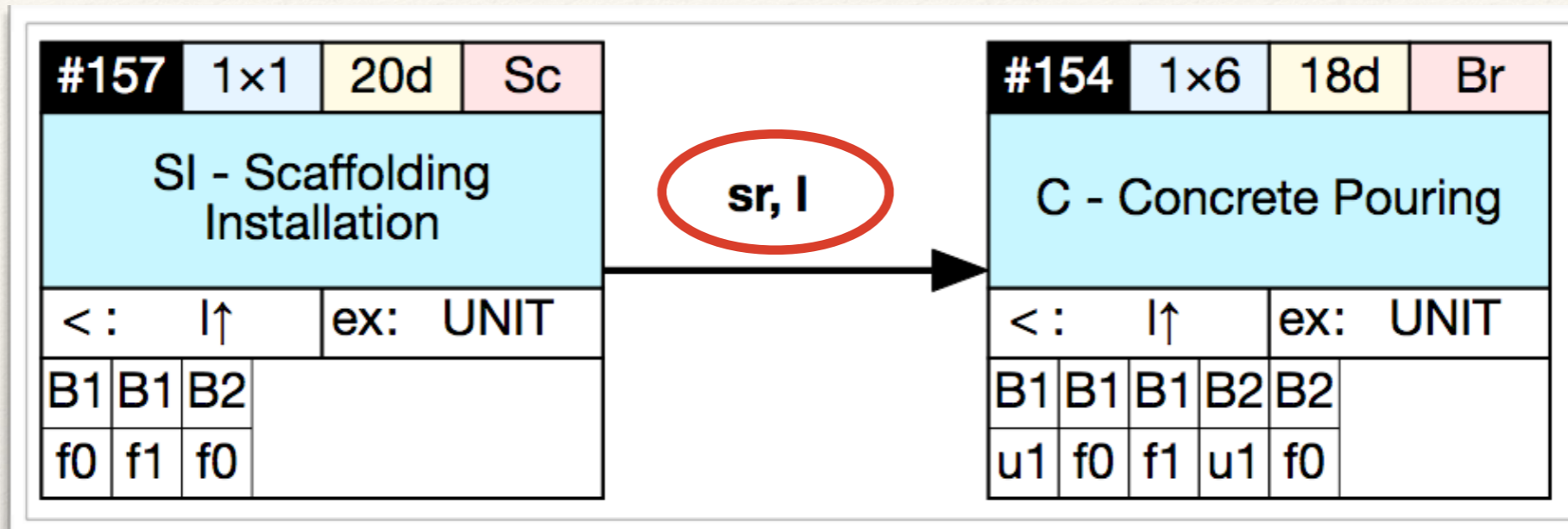


Precedences



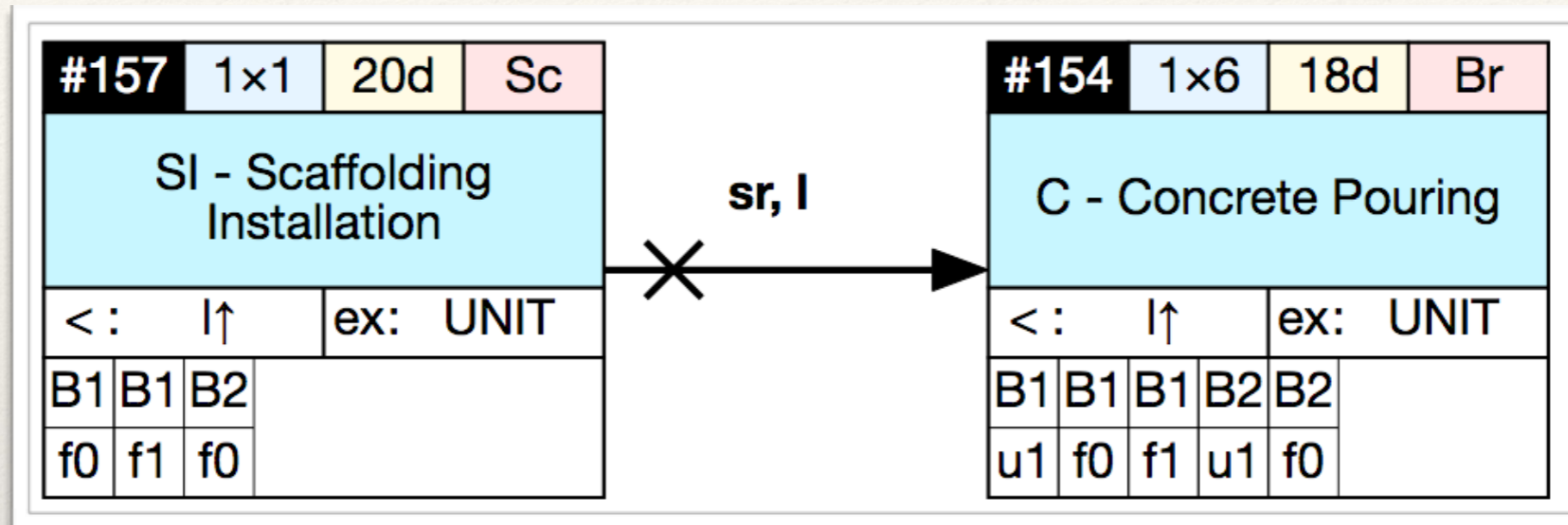
- Precedences between activities

Precedences: Scope



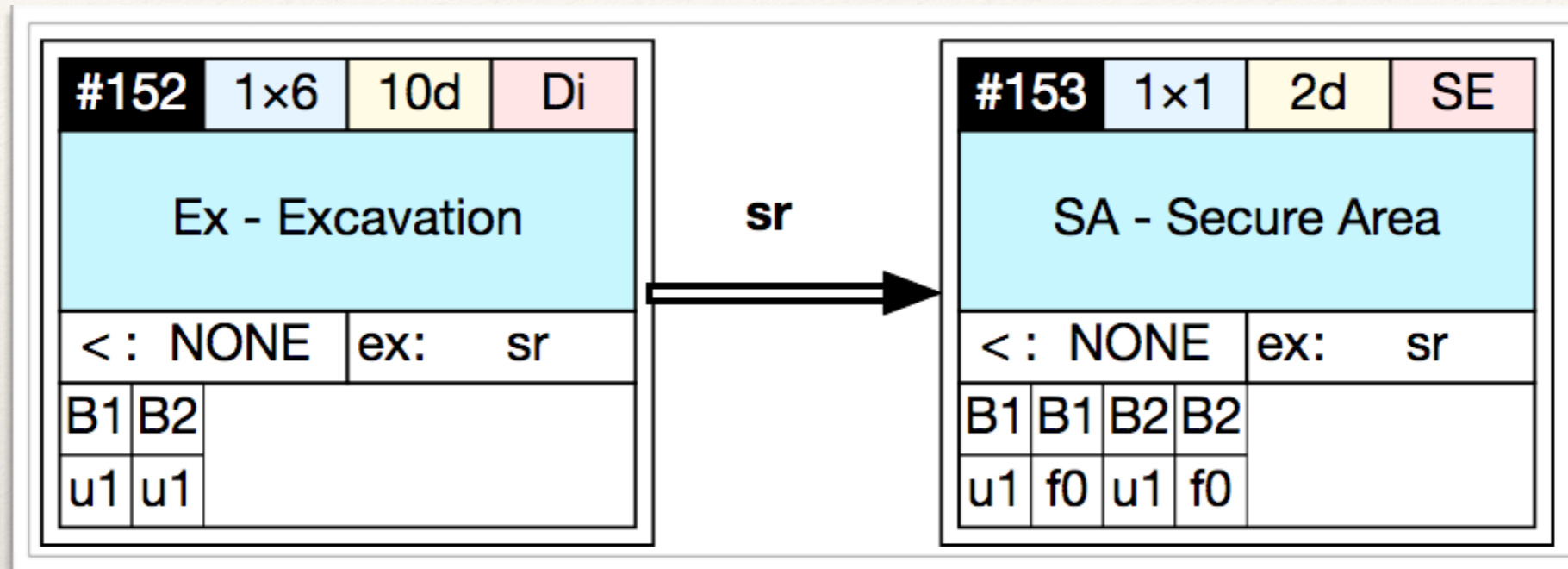
- The **Scope** specialises the precedence (e.g., precedence by <sector, level>)
- By default: **Activity level**

Precedences: Alternate Precedence



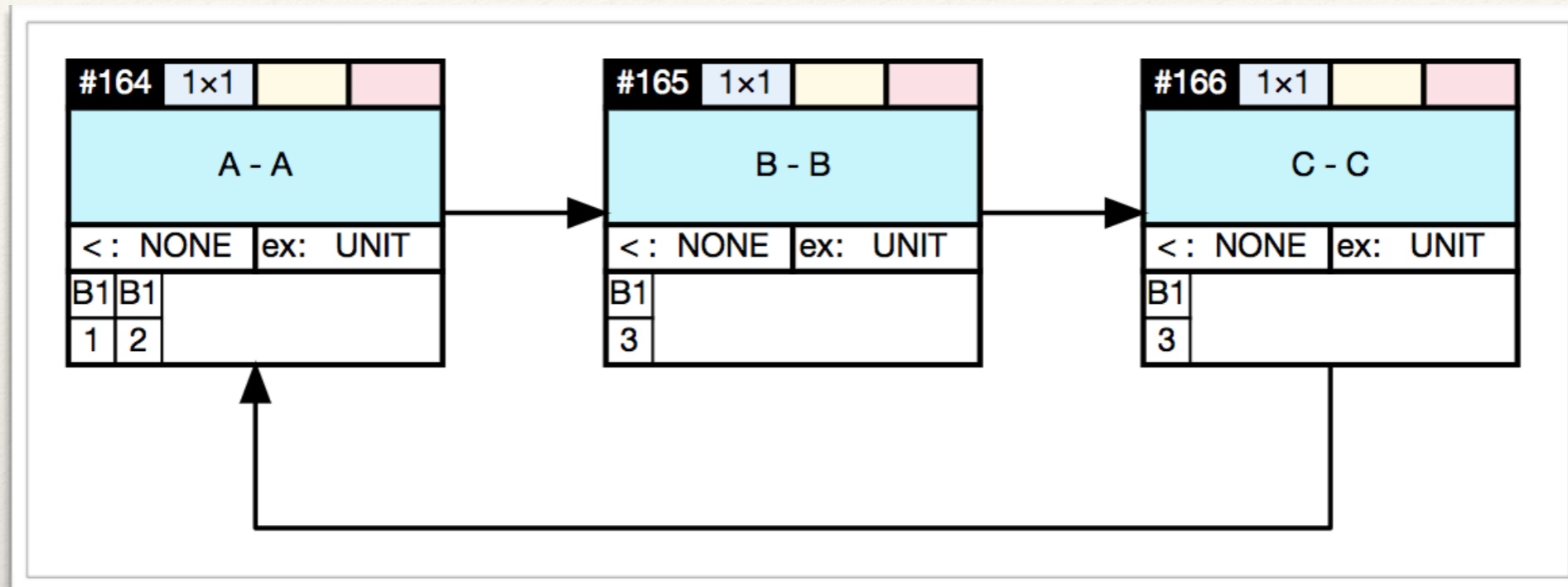
- **Alternation** between antecedent and consequent:
 - antecedent **before** consequent
 - **and** the antecedent has to **wait** for the consequent

Precedences: Chain Precedence

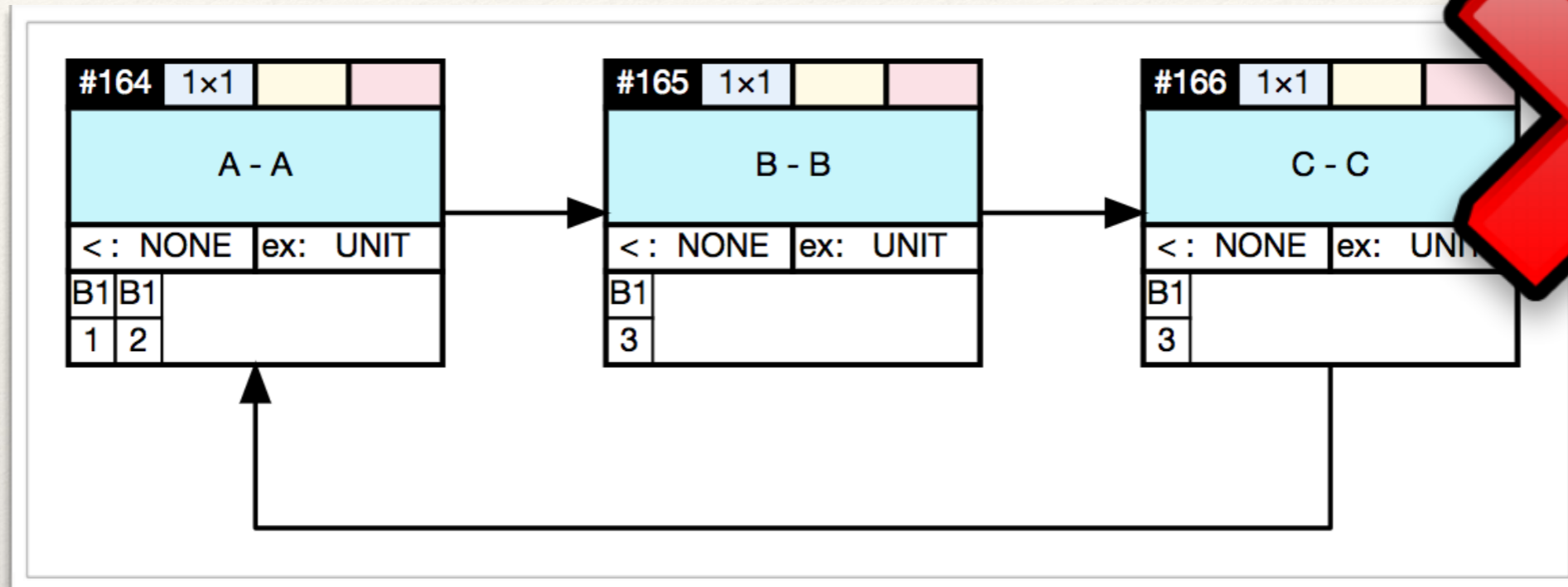


- **Chain** between two activities:
 - **no** other activities can be performed **in-between**

Does my model make sense?

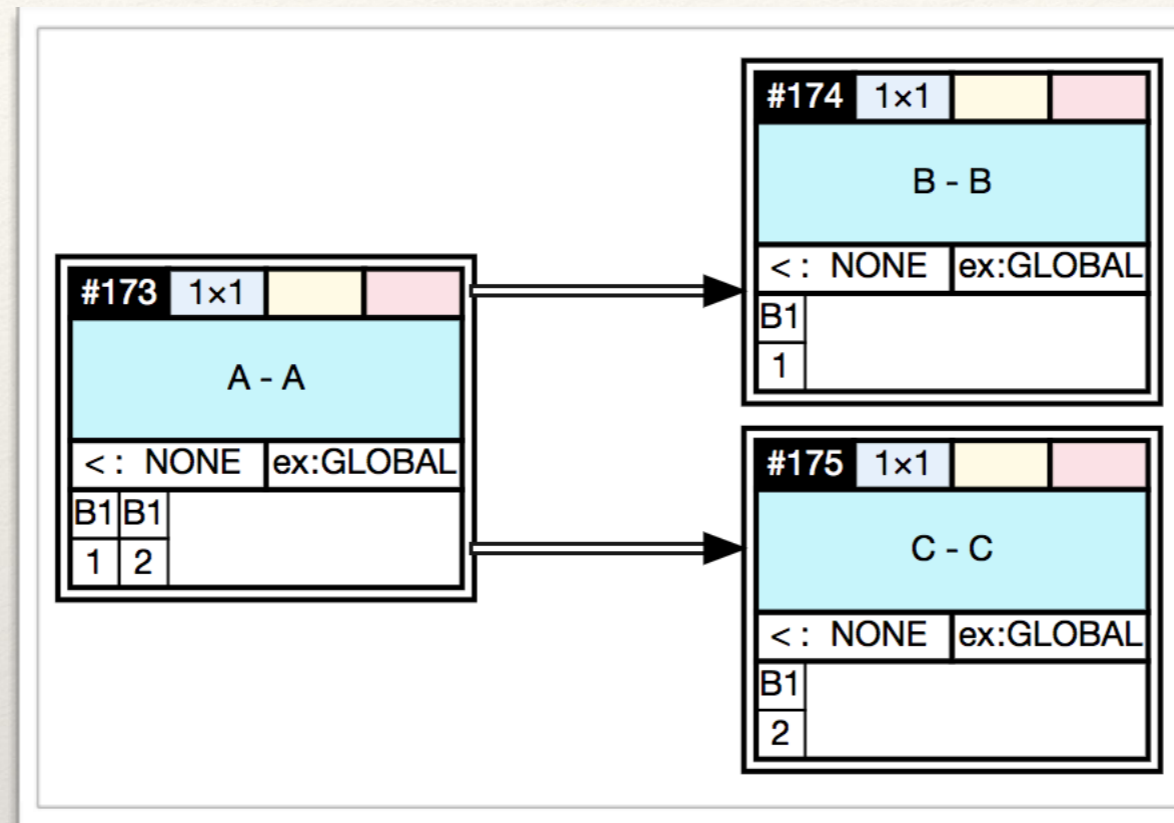


Does my model make sense?



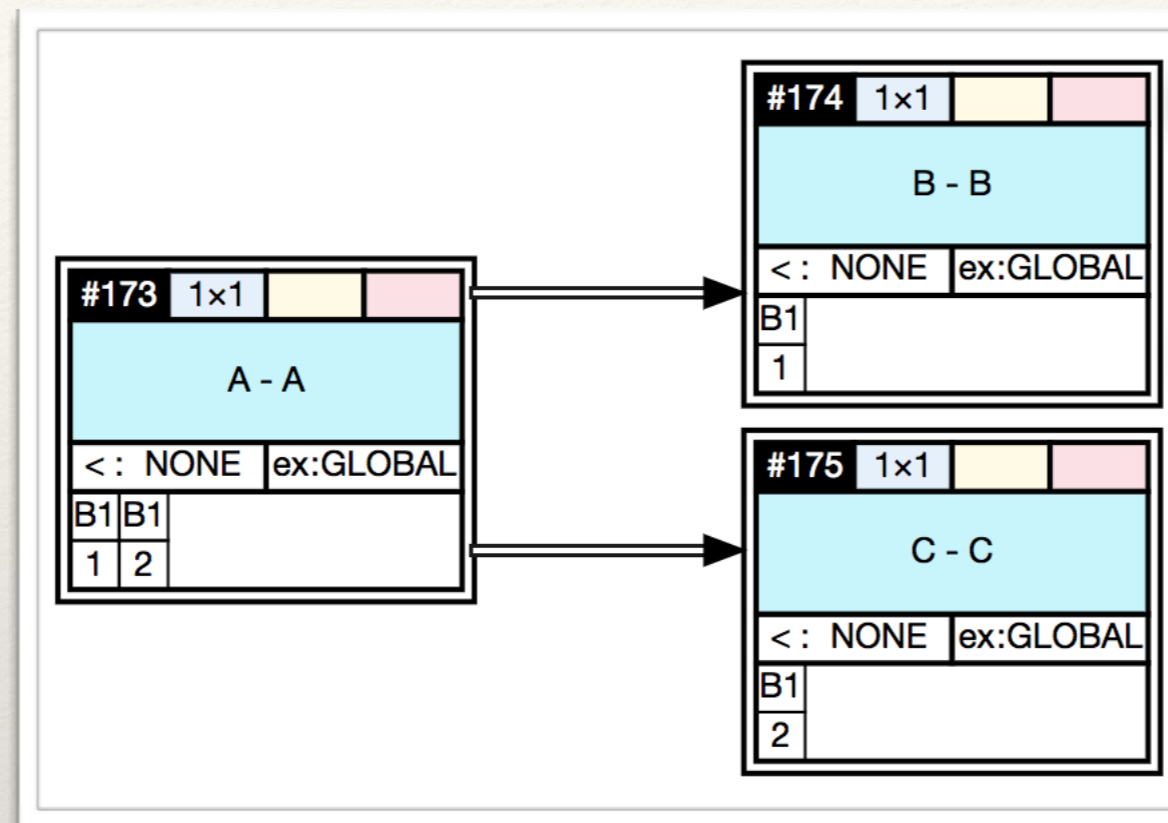
- Is there an execution satisfying all the constraints?
Satisfiability Check

Satisfiability Check



- Is checking for loops enough to determine **Satisfiability**?

Satisfiability Check



- Is checking for loops enough to determine **Satisfiability**?
 - **No,**
 - Consider also the **dependencies**, **scopes** and **locations**

How to Check Satisfiability?

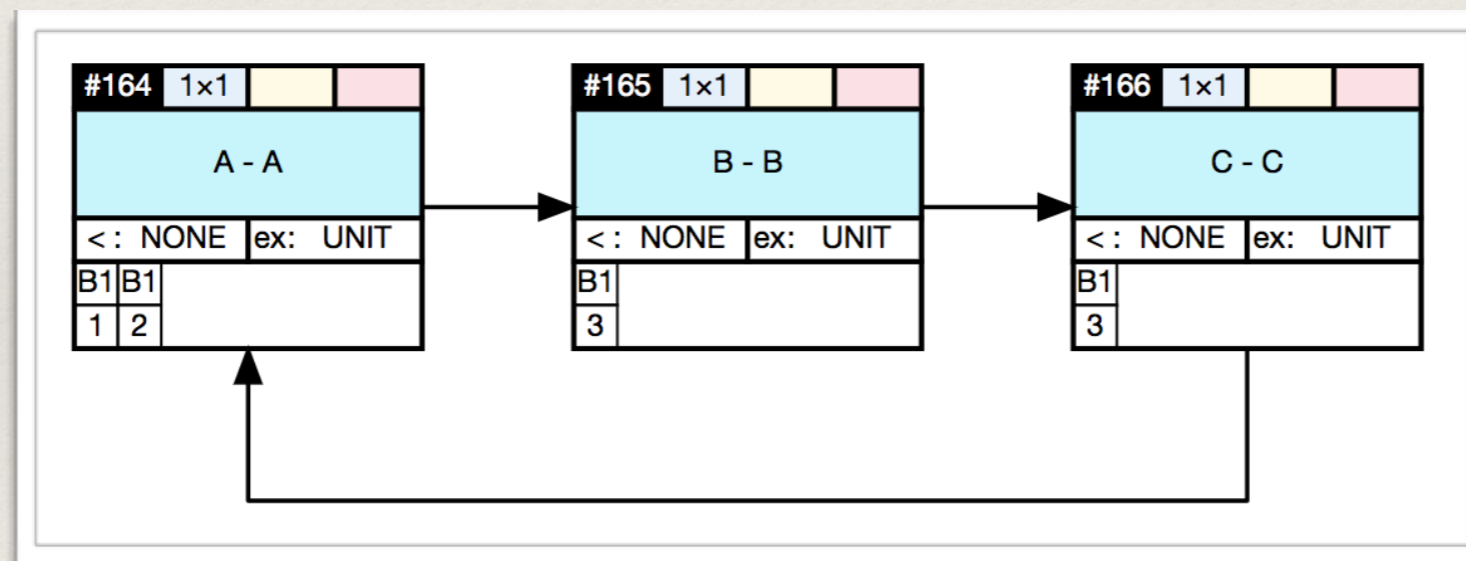
- Our model has a logic based semantics (LTLf)
- We can apply model checking techniques
- We performed some experiments using NuSMV
(state-of-the-art model checker)

How to Check Satisfiability?

	Model	Tasks	Dep.	Loc.	NuSMV
	Sat.	8	9	312	2min 35s
	Non-sat.	8	9	312	>1h

Other Way to Check Satisfiability?

- Translate a Diagram into a Task-Unit (TU) Graph



<A, B1-1>

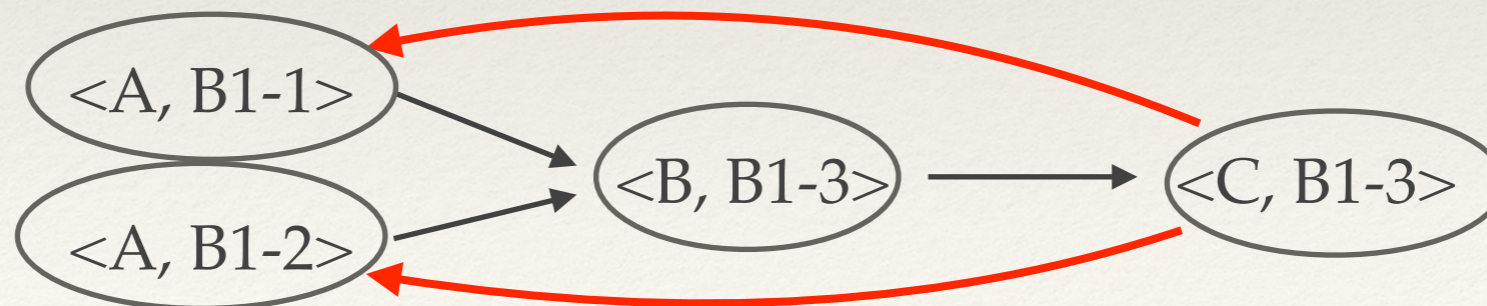
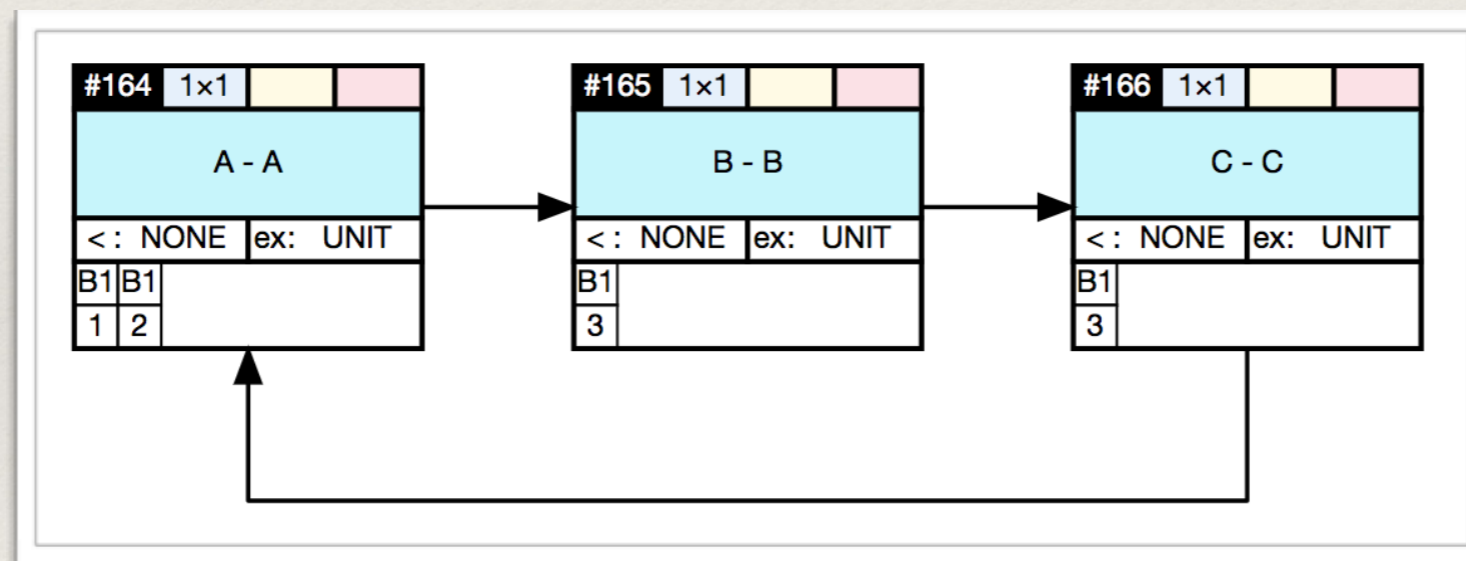
<A, B1-2>

<B, B1-3>

<C, B1-3>

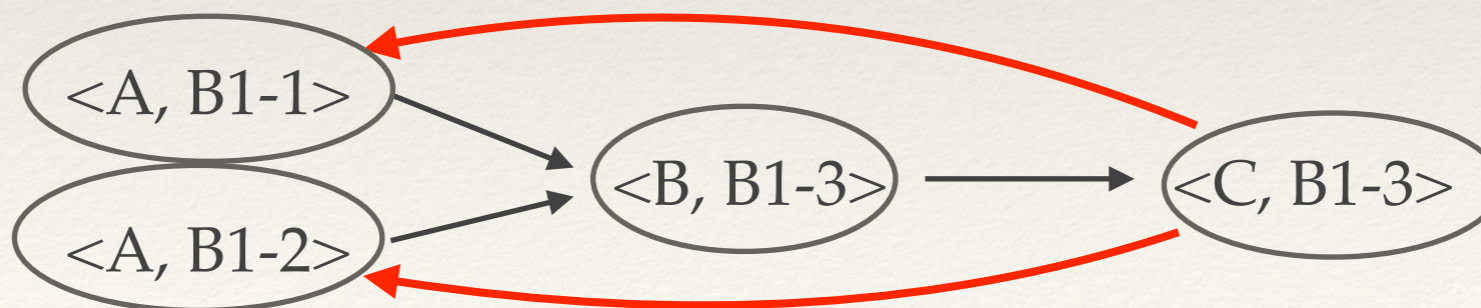
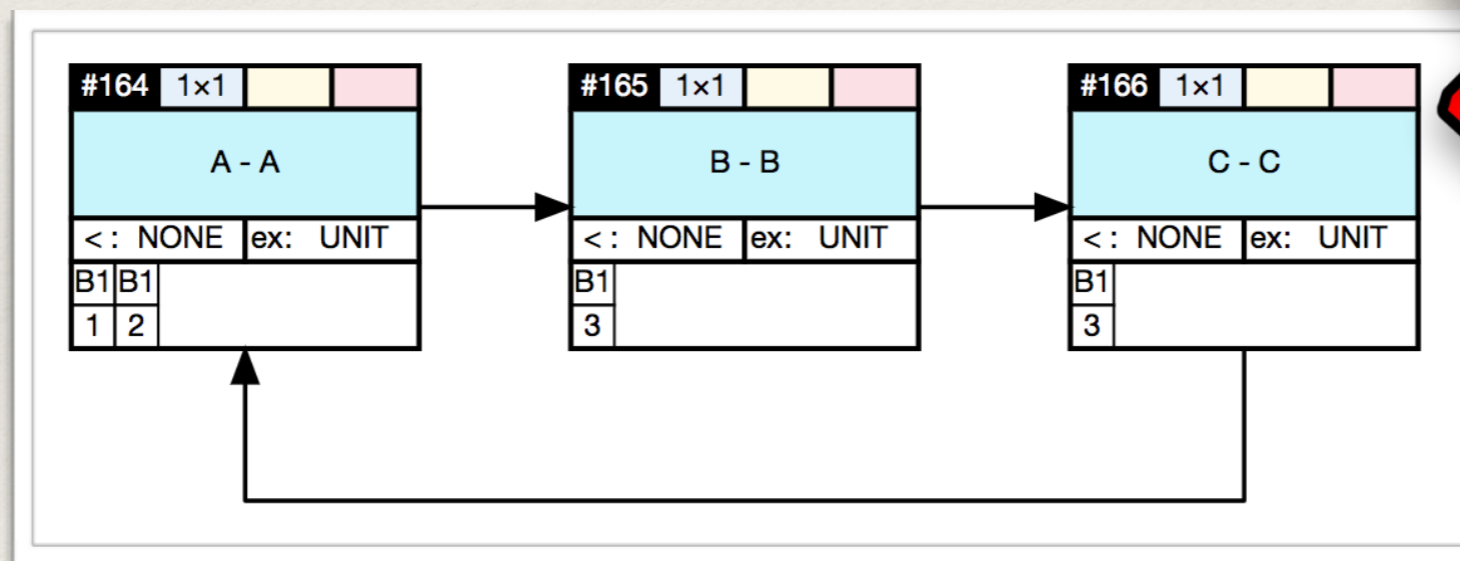
Other Way to Check Satisfiability?

- Translate a Diagram into a Task-Unit (TU) Graph
- Translate the precedences into arrows between TU nodes



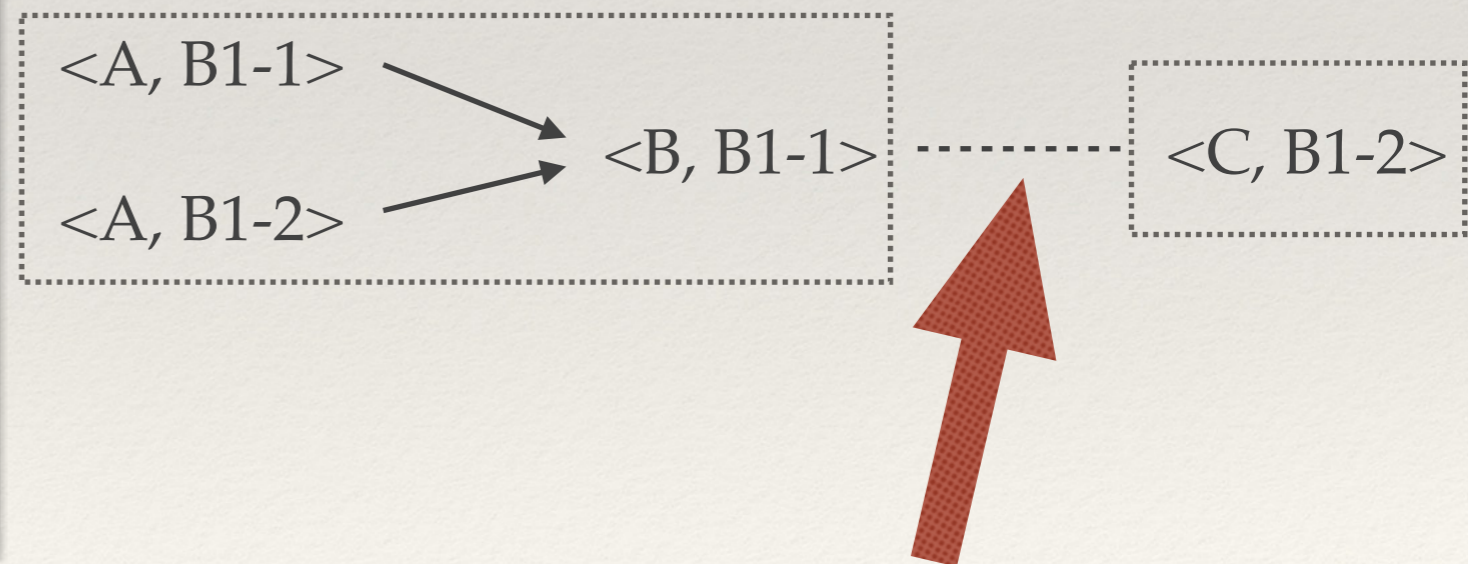
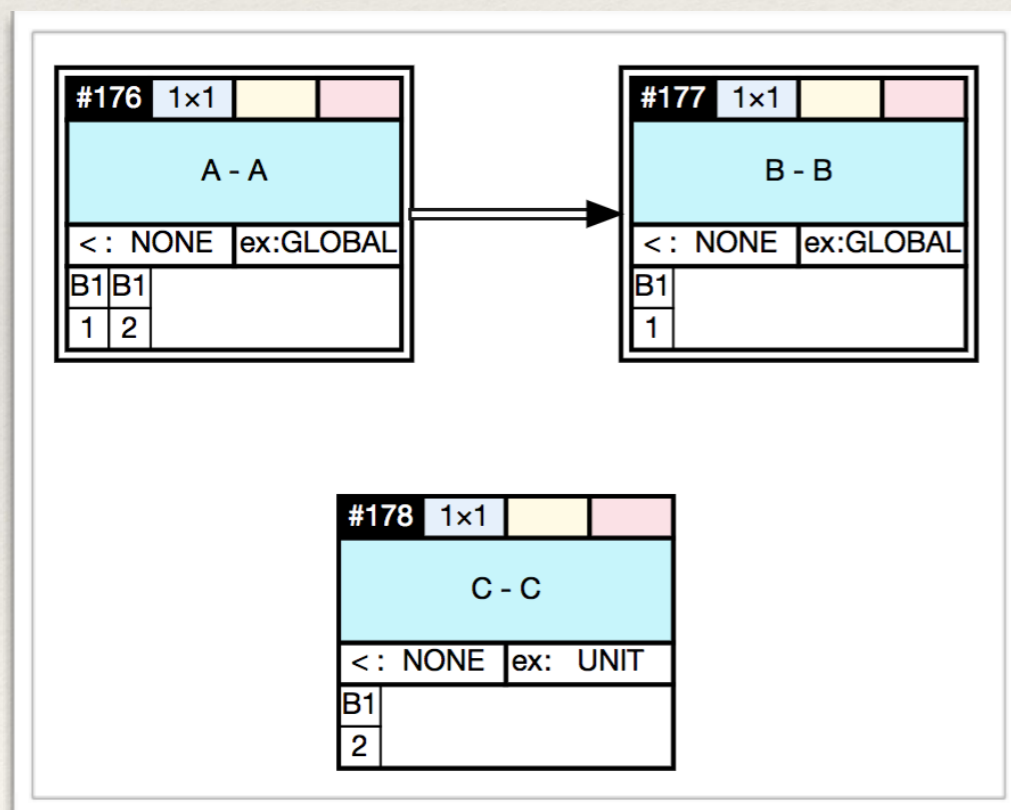
Other Way to Check Satisfiability?

- Translate a Diagram into a Task-Unit (TU) Graph
- Translate the precedences into arrows between TU nodes
- Check for loops



Disjunction in the TU Graph

- Some constraints introduce disjunction
- One has to check possible orientations



Algorithm at a Glance

- **Check for Cycles**
 - Cycles: If the graph contains a cycle then is not orientable



Algorithm at a Glance

- **Check for Cycles**
 - Cycles: If the graph contains a cycle then is not orientable
- **Deterministic Orientation**
 - Direct the undirected edges for which only one orientation is possible





Algorithm at a Glance

- **Check for Cycles**
 - Cycles: If the graph contains a cycle then is not orientable
- **Deterministic Orientation**
 - Direct the undirected edges for which only one orientation is possible
- **Divide&Conquer**
 - Partition the graph so that:
 - orientability can be checked for each subgraph
 - by trying all orientations








Satisfiability Check

	Model	Tasks	Dep.	Loc.	Nodes	Arcs	Edges	NuSMV	US
	Sat.	8	9	312	236	9415	524	2min 35s	27 ms
	Non-sat.	8	9	312	236	10003	521	>1h	5 ms

Satisfiability Check

	Model	Tasks	Dep.	Loc.	Nodes	Arcs	Edges	NuSMV	US
	Sat.	8	9	312	236	9415	524	2min 35s	27 ms
	Non-sat.	8	9	312	236	10003	521	>1h	5 ms
	Bigger	12	14	312 (2)	244	9435	574	>1h	10 ms
	More Edges	12	14	312 (47)	424	15131	1740	>1h	23 ms


Satisfiability Check

	Model	Tasks	Dep.	Nodes	Arcs	Edges	US
	Sat.	8	9	236	9415	524	27 ms
	Non-sat.	8	9	236	10003	521	5 ms
	Bigger	12	14	244	9435	574	10 ms
	Adding Locations	12	14	424	15131	1740	23 ms
	Bigger	480	1291	16,960	1,436,759	678,680	55,866 ms (~1 min)
	Bigger	720	2,526	25,440	3,082,925	1,526,820	379,409 ms (~6.32 min)
	Bigger	960	4,187	33,920	5,217,426	2,714,160	OOM

Summary

- Language **Construction Process Modelling**
 - Graphical
 - Declarative: Captures the constraints (**what** and not **how**)
 - Formal
- Effective algorithm to check satisfiability
- **Demo:** both are implemented in a proof-of-concept tool

Future Work

- COCKPiT:
Collaborative Construction Project management
- Automatic Schedule:
 - Optimised
 - Incremental
 - Align changes: Model  Schedule





BPM 2018

Thank you

Elisa Marengo
Werner Nutt
Matthias Perktold

Free University of Bolzano
